



MERIT beam spot size

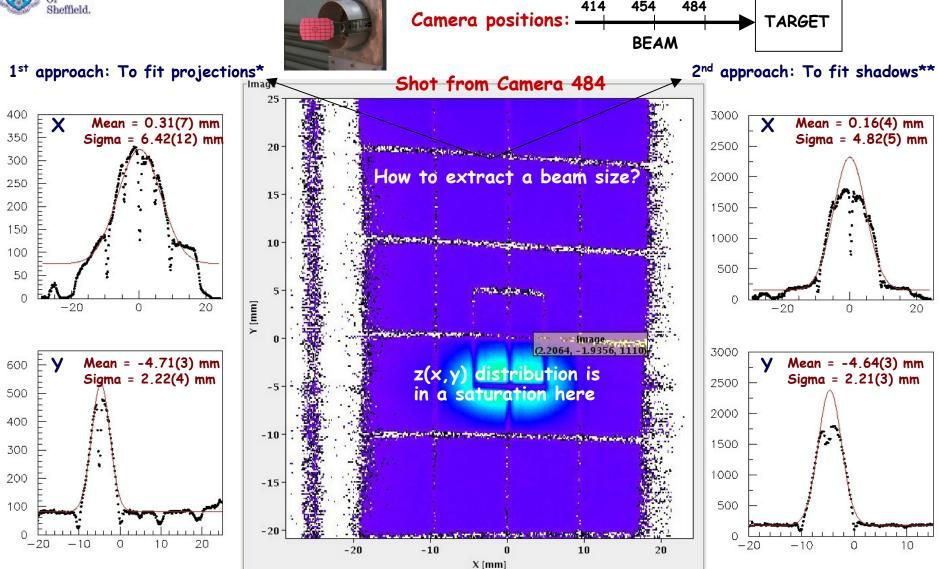
Goran Skoro

18 June 2008

Goran Skoro The University Of Sheffield.

We have 3 beam 'cameras' -> 3 images for every beam pulse

Camera Camera Camera



* Projection for X is $P(x) = \frac{1}{n_y} \sum_{i=1}^{n_y} z(x, y_i)$, similarly for Y.

** Shadow for X is $S(x) = \max[z(x, y_i)], (i = 1, n_y),$ similarly for Y.



Fitting: Procedure



Simple fitting function: Gaussian + 'background'

Fitting algorithm (how to avoid gaps; how to choose initial value of the 'background' term, etc...) was based on the analysis of the 15-20 randomly selected images (after this, completely 'blind' analysis -> no parameters tuning)

In total: 520 beam pulses* \times 3 cameras \times 2 projections = 3120 distributions have been fitted

Result: Table - ntuple (part of it shown below)

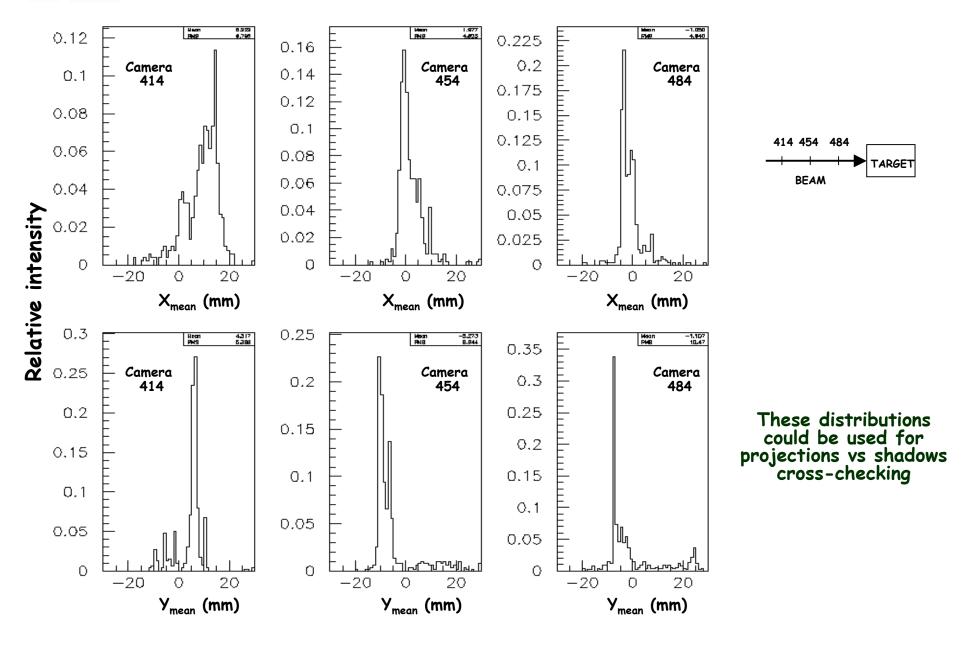
		Camera					Camera 454	Camera 484
Date (ddmmyyyy)	Time (hhmmss)	X _{mean} (mm)	Sigma _× (mm)	y mean (mm)	Sigma _y (mm)	X _{mean} (mm)	Sigma _× Y _{mean} (mm) (mm)	
11112007	115919	9.164	6.153	6.468	5.999	-1.205	6.541 -10.317	•••••
11112007	122348	9.204	6.081	5.331	5.723	-1.234	6.671 -10.043	***********
11112007	123724	9.851	5.720	5.490	4.750	-0.695	5.703 -10.521	•••••
11112007	124959	10.288	5.508	5.880	3.615	0.270	4.599 -10.108	••••••
11112007	125201	7.971	6.342	6.038	3.678	3.236	3.448 -10.015	••••••
11112007	125545	12.105	4.446	5.808	3.516	-1.036	5.781 -10.194	••••••
11112007	125829	13.043	3.803	5.821	3.545	-1.424	5.613 -10.246	••••••
11112007	130436	8.399	6.587	6.164	3.939	1.542	4.026 -10.022	••••••
11112007	130618	11.813	4.675	5.870	3.730	-1.200	5.505 -10.205	••••••
11112007	131023	13.622	3.459	5.709	3.493	-2.083	5.311 -10.238	••••••
11112007	131549	14.397	2.934	5.613	3.350	-3.255	5.101 -10.263	••••••
1111001	101040	11.051	B. 504	0.010	0.000	0.200	0.101 10.200	•••••

This will be used to reconstruct the Run number and to attach this table to the 'global' table with experimental results.

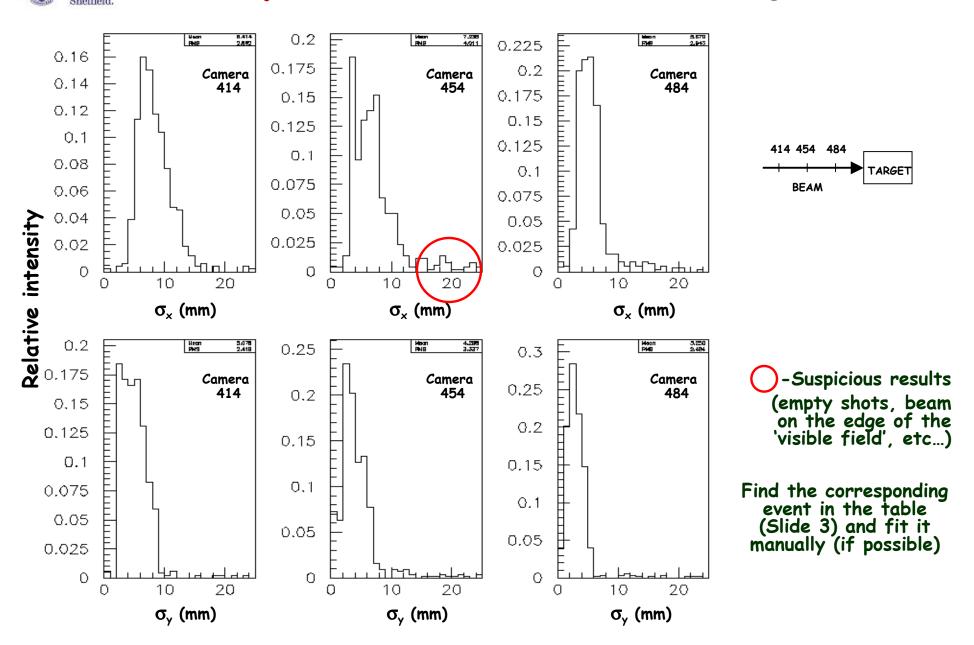
▶ This will be used to recognize a shot with the 'suspicious' fitting result and to fit it 'manually'.



Distributions of the Gaussian means

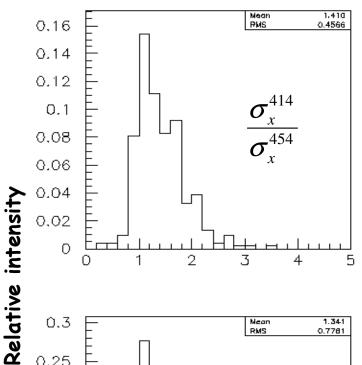


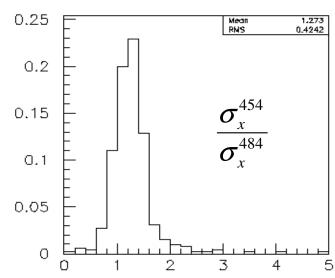
Distributions of the Gaussian sigmas

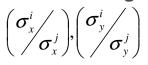


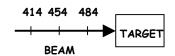


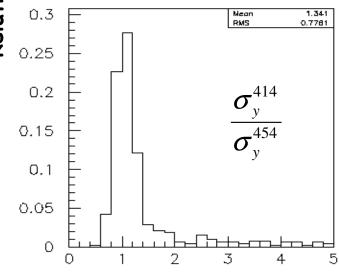
Distributions of the ratios of the Gaussian sigmas

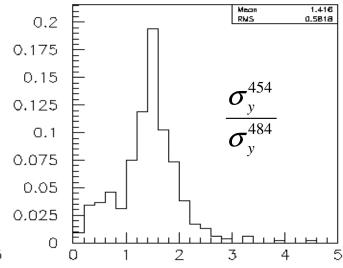










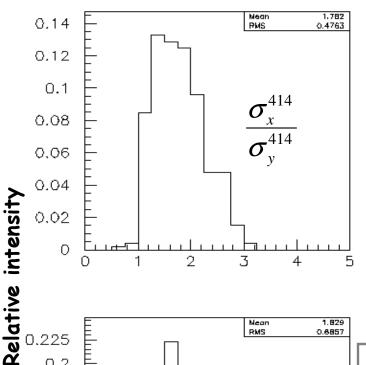


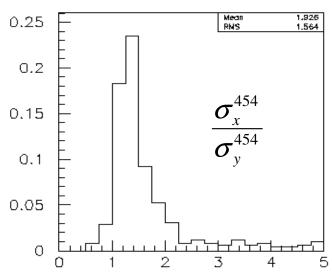
Looks reasonable Shows collimation of the beam when travelling from Camera_414 position towards the target

These distributions could be used for projections vs shadows cross-checking



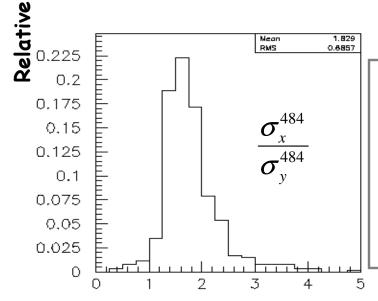
Distributions of the ratios of the Gaussian sigmas











When discussed possible results of this analysis a month ago at Oxford, the conclusion was that it will be a very good progress if we are able to obtain the ratios shown here.

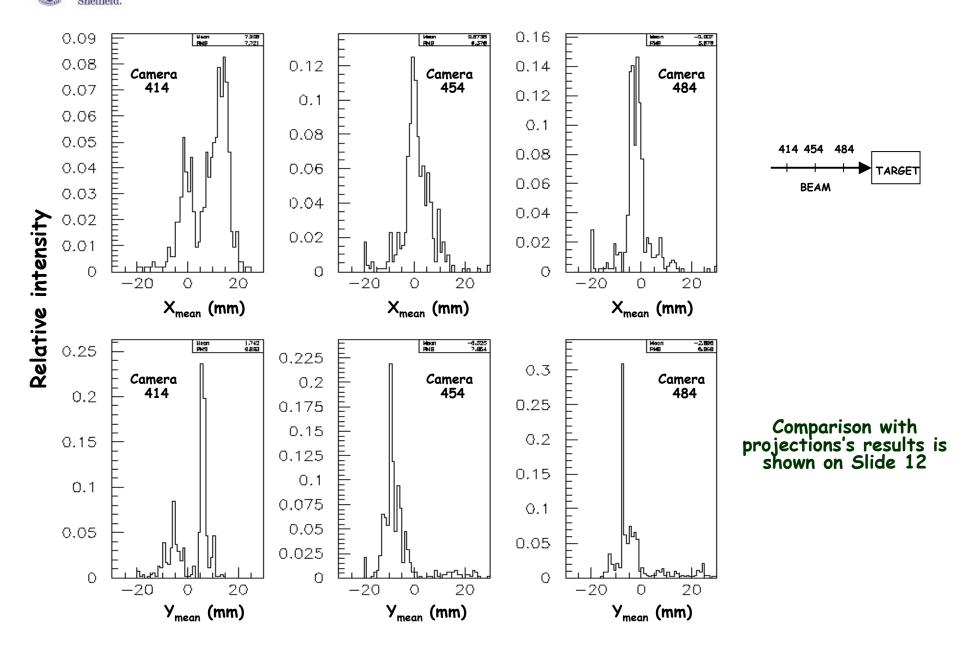
But, maybe the fitting of the 'shadows' will give us a better estimate of the beam size. So the next steps are:

- repeat procedure for the 'shadows';
- compare two sets of the results;
- discuss the results at one of the following MERIT meetings and decide which approach should be used;
- attach the corresponding beam-spot datafile to the 'global' MERIT datafile and start analysis using integrated data.

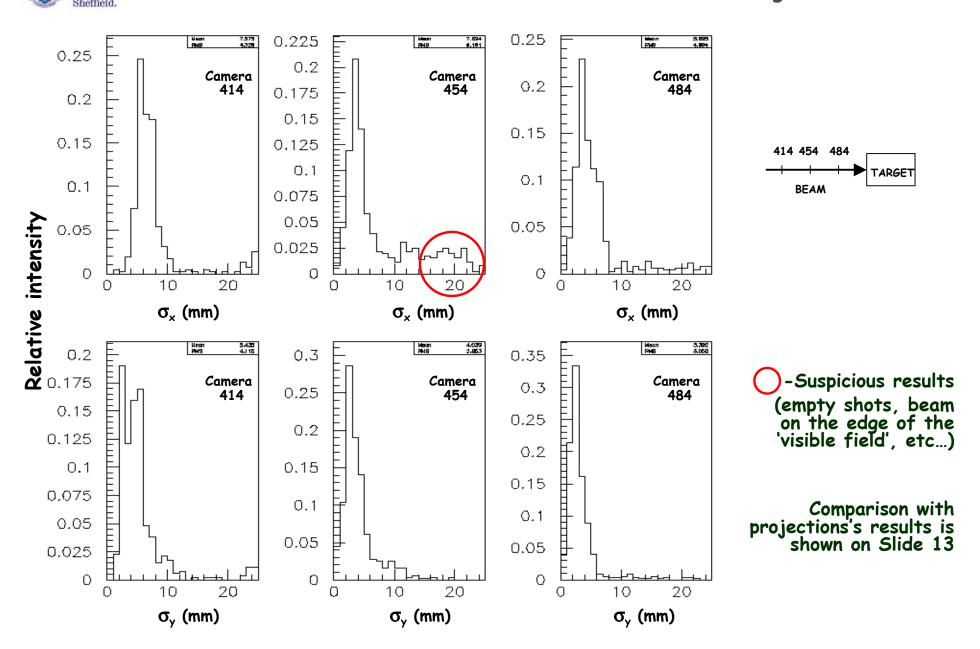
 4 June 2008

Results: see following slides

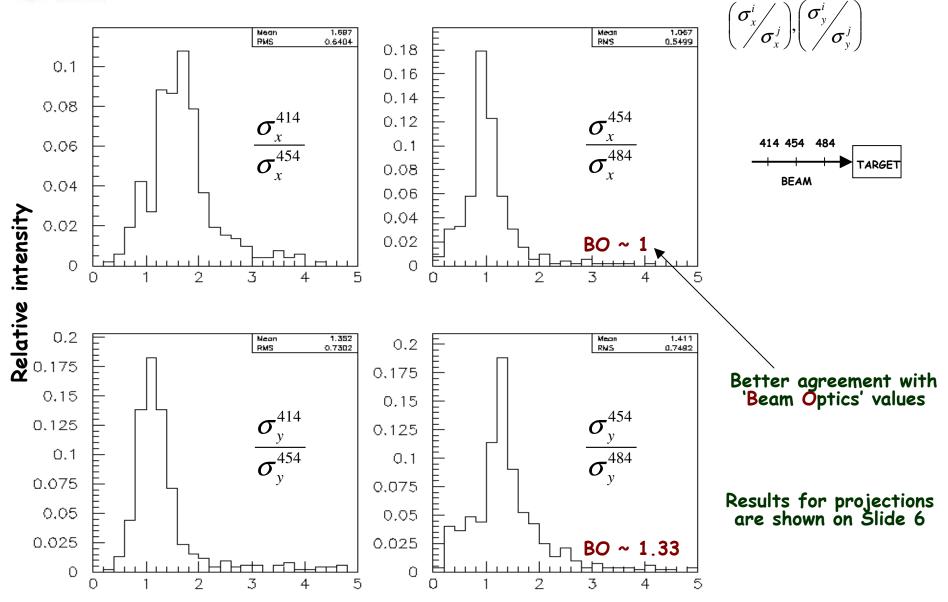
Distributions of the Gaussian means



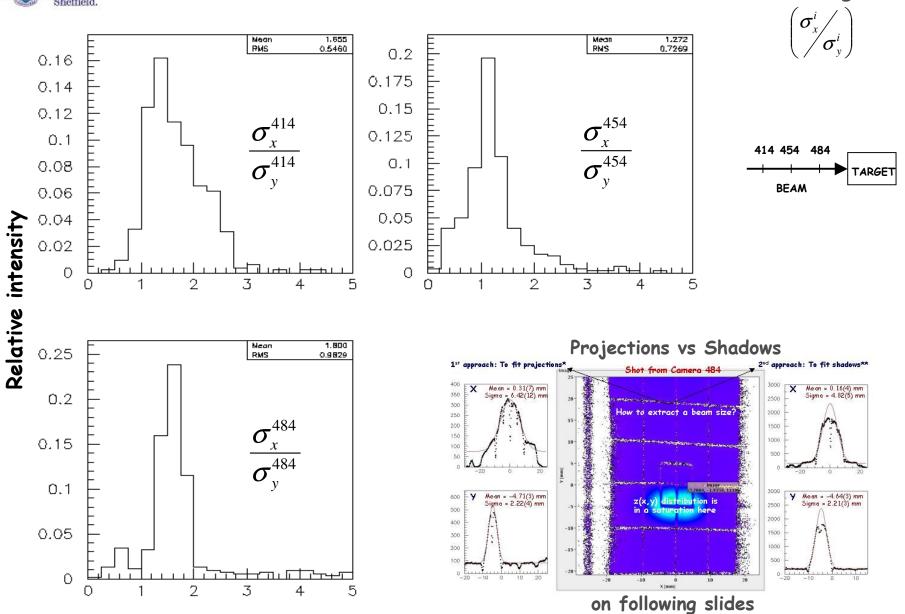
Distributions of the Gaussian sigmas



Distributions of the ratios of the Gaussian sigmas



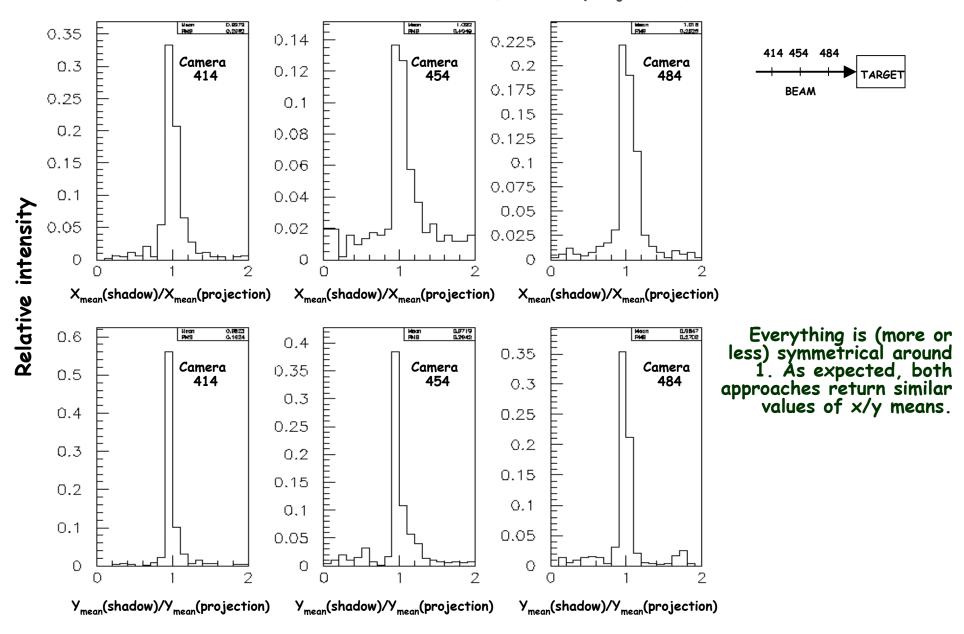
Distributions of the ratios of the Gaussian sigmas





Projections vs Shadows

Distributions of the ratios (shadow/projection) of the Gaussian means





Projections vs Shadows

Distributions of the ratios (shadow/projection) of the Gaussian sigmas

